L011131

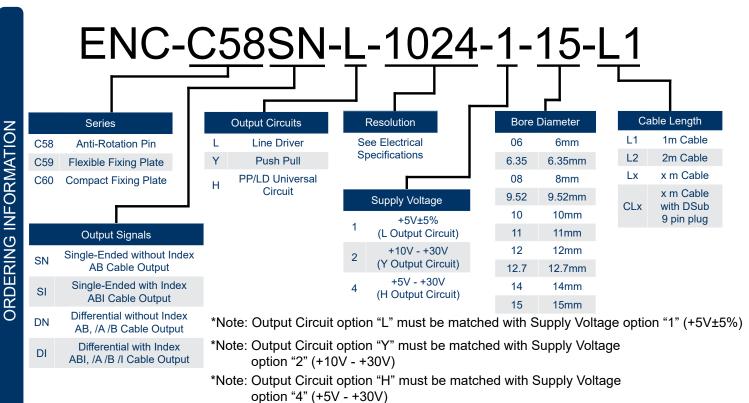
C58/ C59/ C60 Through Hollow Shaft Encoder Series



- Standard Encoder for Heavy Industrial Applications
- Through Shaft up to ø15mm
- 4 to 5,000 Cycles Per Revolution
- Connector or Cable Output
- Optional Index Channel
- Output Circuitry
 - Push-Pull
 - Line Driver
 - PP/LD Universal Circuit
- IP64 Standard
- Custom Options Available
 - Custom Cable Lengths
 - IP67 Protection
 - Termination Connectors

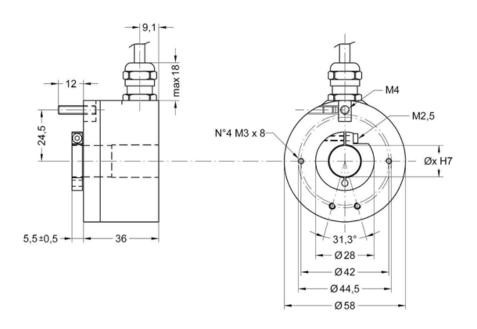


The ENC-C58/C59/C60 is a hollow shaft encoder used for heavy Industrial and feedback applications. These encoders are offered with resolutions ranging from 4 to 5000 CPR (model dependent). These encoders fit shaft diameters up to 15mm, but reducing sleeves are available for shaft diameters as small as 6mm. With various mounting options, three output circuitry options, and input voltage ranges, these encoders can be customized to fit your applications needs.

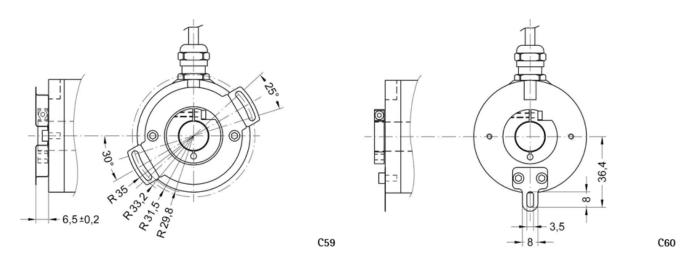


*Note: For customization options, please contact our applications engineers.



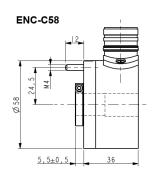


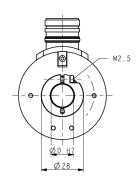
C58

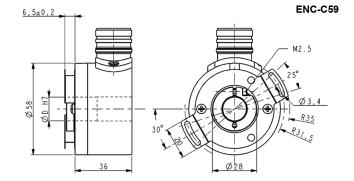


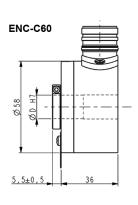
All units are in mm

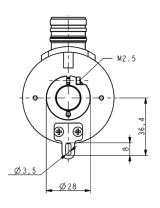












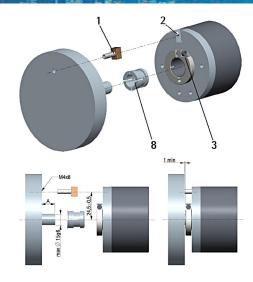
Differential Pinout		
Color	Description	
Yellow	Α	
Blue	/A	
Green	В	
Orange	/B	
White	1	
Grey	/I	
Red	+VDC	
Black	OVDC	
Shield	Shield	

Single-Ended Pinout		
Color	Description	
Brown	Α	
Blue	В	
White	1	
Red	+VDC	
Black	OVDC	
Shield	Shield	



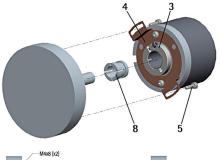
C58 Series

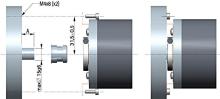
- Fasten the anti-rotation pin 1 to the rear of the motor.
- · Mount the encoder on the motor shaft using the reducing sleeve 8, avoid forcing the encoder shaft.
- Insert the anti-rotation pin 1 to the slot on the flange of the encoder; this ensures its place by grub screw 2.
- Fix the collar 3 to the encoder shaft.



C59 Series

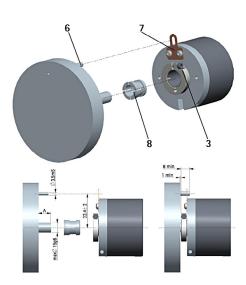
- · Mount the encoder on the motor shaft using the reducing sleeve 8, avoid forcing the encoder shaft.
- Fasten the fixing plate 4 to the rear of the motor using two M4 cylindrical head screws
- Fix the collar 3 to the encoder shaft.







- Fix the tempered pin 6 to the rear of the motor
- Mount the encoder on the motor shaft using the reducing sleeve 8, avoid forcing the encoder shaft.
- Make sure the anti-rotation pin6 is inserted properly into the fixing plate 7.
- Fix the collar 3 to the encoder shaft.





Mechanical Specifications		
Housing:	Anti Corodal, UNI EN AW-6082	
Shaft Rotational Speed:	6000 RPM Max	
Starting Torque at 20°C:	≤1.5 Ncm	
Hollow Shaft Diameter:	14, 15 mm	
Shaft Loading (Axial, Radial):	30N Max	
Moment of Inertia	30 gcm ²	
Bearings Life:	10 ⁹ rev. min.	
Weight:	0.6625lb	

Electrical Specifications		
Resolution (Other CPR Upon Request):	4, 5, 10, 12, 15, 16, 20, 24, 25, 30, 35, 36, 40, 45, 50, 60, 70, 80, 90, 100, 120, 122, 125, 142, 150, 180, 200, 236, 250, 256, 267, 300, 314, 360, 400, 410, 433, 435, 471, 500, 600, 635, 720, 784, 875, 900, 1000, 1024, 1250, 1800, 2000, 2048, 2500, 3600, 4000, 4096, 5000	
Power Supply :	+5V±5%, +10V to +30V, +5V to +30V	
Output Circuits:	Push-Pull, Line Driver, PP/LD	
Output Current (Per Channel):	40 mA Max.	
Output Frequency:	60 kHz Max.	
Input Current:	70 mA Max.	
Protection:	Against Inversion of Polarity (Except +5V Version) Outputs are Protected Against Short-Circuit (Except Line Driver Version)	
Optoelectronic Life:	100000 Hours Min	

Environmental Specifications	Min	Max	Units
Operating Temperature	-20	70	°C
Storage Temperature	-20	80	°C
Protection Level		IP64	
Option	IP65 Protection	n (3000 RPM Max, T	orque 1 Ncm)

Custom Options	
Protection	IP65
Cable Lengths	Up to 100m
EDE9S	9 Pin DSub Mating Connector